



### Submission Form for the 2012 IEEE International Conference on Robotics and Automation

[Home](#) [Log In](#) [PIN](#) [Refresh](#) [Help...](#)

53:07

Warning: [Test your pdf file](#) before uploading it

[Cancel](#)

Submit Student Travel Support Application to 2012 IEEE International Conference on Robotics and Automation	
<b>Submission Information Section</b>	Use this page to submit a contributed paper Complete the fields in this section and click on the Next button All fields are required, including the keywords  Warning: The browser Back button has been disabled. Do not use it during the submission
Type of submission	<b>Student Travel Support Application</b>
Title of the paper*	<input type="text" value="--Enter the title of the paper--"/>
How many authors does the paper have?*	<input type="text" value="--Select a number--"/>
	Follow the link <a href="#">PIN</a> to look up or register your Personal Identification Number (PIN) and the PINs of all your co-authors in a separate browser window  List the PINs in the order in which the authors appear in the paper and check the corresponding author
Keywords*	<input type="text" value="Click to choose an ordered set of keywords"/>
Abstract* Must fit in box Excess text is truncated Plain text only	<input type="text" value="--Enter the abstract--"/>
Commitment*	By uploading this manuscript I certify that  (1) the manuscript is submitted with the full knowledge and consent of all co-authors (if any), and that I will undertake to keep my co-authors informed of all correspondence about the manuscript.  (2) contents of this manuscript are original and it is not being submitted simultaneously for consideration towards publication in another conference or journal. I understand that all submissiona will be checked by the <b>iThenticate</b> tool for plagiarism and excessive reuse of authors own existing material. In cases of plagiarism or excessive reuse, all results will be reported to the IEEE for further investigation.  (3) in the event that the manuscript is accepted, the authors will provide a final version that will fundamentally correspond, in length and contents, to the submitted version, except for parts that might be added or modified to comply with the reviewers' suggestions. It is considered unethical to shorten or otherwise alter the final version in ways that make it weaker than what was approved by the reviewers.  (4) none of the authors are on the IEEE Restricted Author List.  I also understand that

(1) by submitting my manuscript through the RAS conference paper management system, I am permitting the RAS society access to my contact information and research interests. I agree that this data may only be used by the RAS designated users to contact me regarding future events sponsored by the society and to assist its editorial board to identify qualified reviewers for peer review of submissions to its conferences.

(2) if my manuscript is accepted by the conference, I or one of my co-authors or colleagues will attend the conference to present the paper and will comply with the conference registration policy.

(3) failure to comply with above may lead to the Robotics and Automation Society preventing me and my co-authors from submitting manuscripts to future events.

I agree

53:07

Next

Next

Click on the Next button to verify the data that has been entered and to continue to the File Upload Section

[Cancel](#)

Technical Content © IEEE Robotics & Automation Society

This site is protected by copyright and trademark laws under US and International law. All rights reserved. © 2002-2012 PaperCept, Inc. Page generated 2012-02-11 06:01:16 PST [Terms of use](#)

